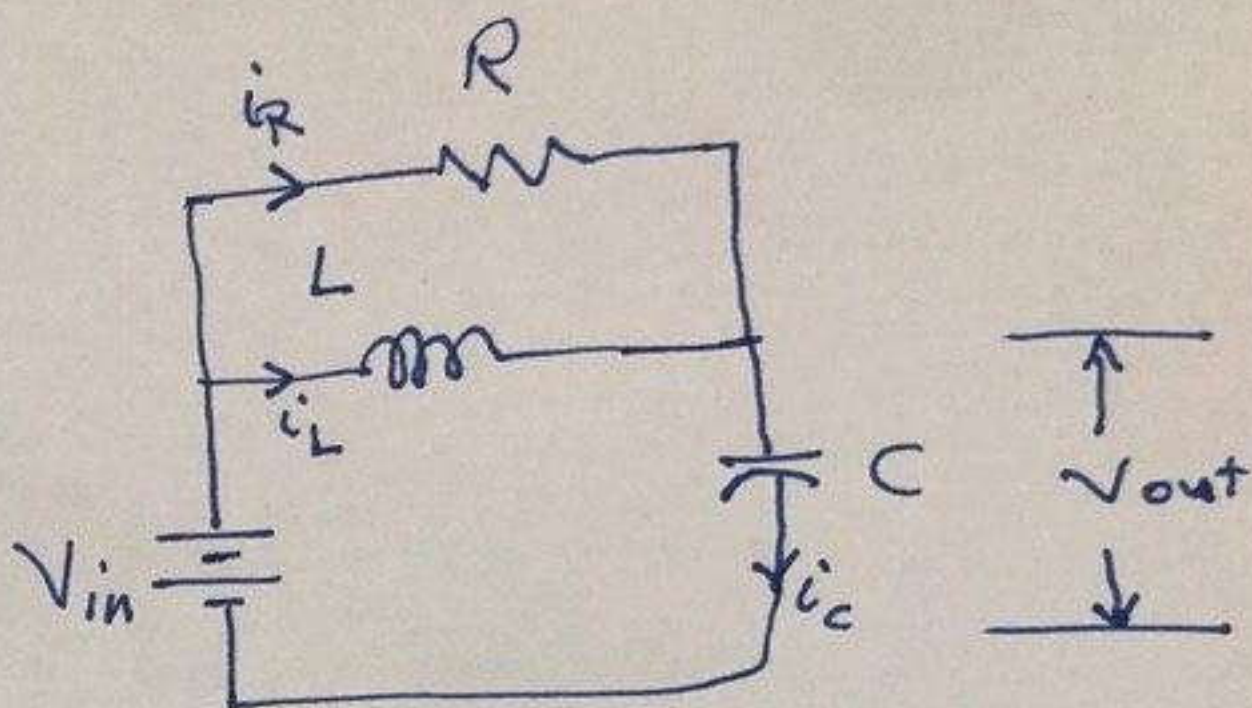


# Lec. 1

## H.W. 1



$$i_C = C \frac{dV_C}{dt}$$

$$V_L = L \frac{di_L}{dt}$$

$$V_{out} = V_C = x_1$$

$$V_{out} = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$V_{in} = V_L + V_C$$

$$V_{in} = L \frac{di_L}{dt} + V_C$$

let

$$i_L = x_2 \quad V_C = x_1$$

$$\dot{x}_2 = \frac{1}{L} V_{in} - \frac{1}{L} x_1 \quad \text{--- ①}$$

$$V_{in} = V_R + V_C = (i_C - i_L)R + V_C$$

$$V_{in} = i_C R - i_L R + V_C$$

$$= CR \frac{dV_C}{dt} - i_L R + V_C$$

$$= CR \dot{x}_1 - R x_2 + x_1$$

$$CR \dot{x}_1 = V_{in} + R x_2 - x_1$$

$$\dot{x}_1 = \frac{V_{in}}{CR} + \frac{x_2}{C} - \frac{x_1}{CR} \quad \text{--- ②}$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} -\frac{1}{CR} & \frac{1}{C} \\ -\frac{1}{L} & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} \frac{1}{CR} \\ \frac{1}{L} \end{bmatrix} V_{in}$$

$$V_{out} = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$



$$A = \begin{bmatrix} -\frac{1}{CR} & \frac{1}{C} \\ -\frac{1}{L} & 0 \end{bmatrix} \quad B = \begin{bmatrix} \frac{1}{CR} \\ \frac{1}{L} \end{bmatrix}$$

$$C^T = [1 \quad 0] \quad D = 0$$

$$G(s) = C^T (sI - A)^{-1} B$$

$$\textcircled{1} (sI - A) = \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} -\frac{1}{CR} & \frac{1}{C} \\ -\frac{1}{L} & 0 \end{bmatrix} = \begin{bmatrix} s + \frac{1}{CR} & -\frac{1}{C} \\ \frac{1}{L} & s \end{bmatrix}$$

$$\text{cof} \{sI - A\} = \begin{bmatrix} s & \frac{1}{L} \\ \frac{1}{C} & s + \frac{1}{CR} \end{bmatrix}$$

$$\text{adj} \{sI - A\} = \begin{bmatrix} s & \frac{1}{C} \\ -\frac{1}{L} & s + \frac{1}{CR} \end{bmatrix}$$

$$\det \{sI - A\} = \left(s + \frac{1}{CR}\right)s + \frac{1}{C} \cdot \frac{1}{L} = s^2 + \frac{s}{CR} + \frac{1}{CL}$$

$$(sI - A)^{-1} = \frac{\begin{bmatrix} s & \frac{1}{C} \\ -\frac{1}{L} & s + \frac{1}{CR} \end{bmatrix}}{s^2 + s \frac{1}{CR} + \frac{1}{CL}}$$







② current in the second capacitor.

④

$$i_{L_2} = i_{C_2} = C_2 \frac{dV_{C_2}}{dt}$$

$$X_4 = C_2 \dot{X}_2 \Rightarrow \dot{X}_2 = \frac{X_4}{C_2} \quad \text{--- (2)}$$

③ loop abefa

$$E = V_{R_1} + V_{L_1} + V_{R_2} + V_{C_1}$$

$$E = i_{L_1} R_1 + L_1 \frac{di_{L_1}}{dt} + (i_{L_1} - i_{L_2}) R_2 + V_{C_1}$$

$$E = X_3 R_1 + \dot{X}_3 L_1 + X_3 R_2 - X_4 R_2 + X_1$$

$$\dot{X}_3 = \frac{E}{L_1} - \frac{X_1}{L_1} - \frac{X_3 (R_1 + R_2)}{L_1} + \frac{X_4 R_2}{L_1} \quad \text{--- (3)}$$

④ loop bcdeb

$$V_{C_2} + V_{R_3} + V_{L_2} + V_{C_1} + V_{R_2} = 0$$

$$V_{C_2} + i_{L_2} R_3 + L_2 \frac{di_{L_2}}{dt} + V_{C_1} + (i_{L_2} - i_{L_1}) R_2 = 0$$

$$X_2 + X_4 R_3 + L_2 \dot{X}_4 + X_1 + X_4 R_2 - X_3 R_2 = 0$$



$$\dot{X}_4 = -\frac{X_1}{L_2} - \frac{X_2}{L_2} + \frac{R_2}{L_2} X_3 - \frac{X_4 (R_2 + R_3)}{L_2} \quad (5)$$

$$\begin{bmatrix} \dot{X}_1 \\ \dot{X}_2 \\ \dot{X}_3 \\ \dot{X}_4 \end{bmatrix} = \begin{bmatrix} 0 & 0 & \frac{1}{C_1} & -\frac{1}{C_1} \\ 0 & 0 & 0 & \frac{1}{C_2} \\ -\frac{1}{L_1} & -\frac{(R_1 + R_2)}{L_1} & 0 & \frac{R_2}{L_1} \\ -\frac{1}{L_2} & -\frac{1}{L_2} & \frac{R_2}{L_2} & -\frac{(R_2 + R_3)}{L_2} \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \\ X_3 \\ X_4 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad \text{E}$$

## Lecture 2 H.W

Q1

$$R_{xy}(-2) = \frac{(-2.4)(-0.25) + (1)(3.6) + (-1.75)(1.6)}{3}$$

$$= 0.466$$

$$R_{xy}(3) = \frac{(0.95)(0.5) + (2)(3)}{2} = 3.2375$$

$$R_{yx}(2) = R_{xy}(-2) = 0.466$$

$$R_{yx}(-1) = \frac{(0.5)(3.6) + (3)(1.6) + (-2.4)(0.95) + (1)(2)}{4} = 1.58$$



$$\text{Q2} \quad R_{xy}(-3) = \frac{((1.6)(1) + (3)(1) + (3.4)(2) + (4)(3) + (2)(2))}{5} \quad (6)$$

$$= 5.48$$

$$R_{yy}(3) = \frac{((3)(1) + (2)(1) + (1)(2) + (3)(3) + (4)(2))}{5} = 4.8$$

$$R_{yx}(2) = \frac{((0.4)(1) + (1.6)(1) + (3)(2) + (3.4)(3) + (4)(2) + (2)(1))}{6}$$

$$= 4.7$$

$$R_{xy}(3) = \frac{((3)(0.1) + (2)(0.3) + (1)(0.4) + (3)(1.6) + (4)(3))}{5}$$

$$= 3.62$$


---

$$\text{Q3} \quad R_{xy}(1) = \frac{((0.4)(-2.2) + (-3.2)(-1.8) + (-0.8)(-2.2) + (1.4)(-1.8))}{4}$$

$$= 1.03$$

$$R_{yx}(1) = \frac{((-3.2)(-0.8) + (-2.2)(-2.2) + (1.4)(-1.8) + (3.4)(-0.8))}{4}$$

$$= 0.54$$

$$R_{yy}(2) = \frac{((-1.8)(-0.8) + (-0.8)(-2.2) + (-1.8)(-1.8))}{3} = 2.146$$

$$R_{xx}(-2) = \frac{((-2.2)(0.4) + (1.4)(-3.2) + (3.4)(-2.2))}{3} = -4.28$$



Q4  $R_{xx}(\tau) = V^2 \left[ 1 - \frac{|\tau|}{T} \right]$

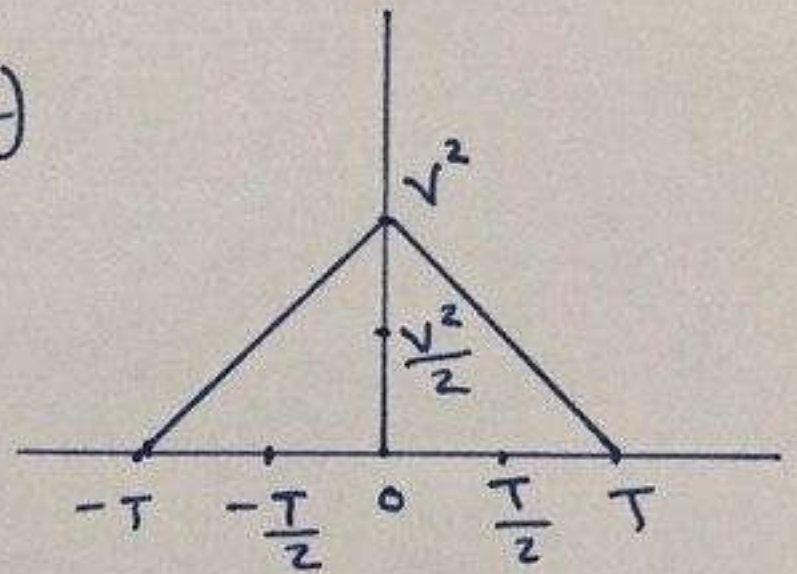
$-T \leq \tau \leq T$

(7)

① at  $\tau = 0$   $R_{xx} = V^2$

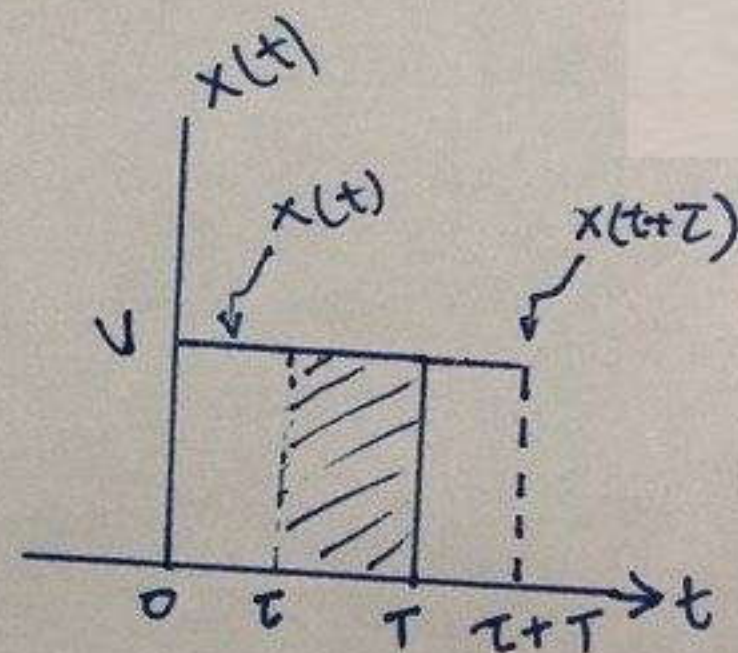
② at  $\tau = \pm \frac{T}{2}$   $R_{xx} = V^2 \left( 1 - \frac{T/2}{T} \right)$   
 $= \frac{V^2}{2}$

③ at  $\tau = \pm T$   $R_{xx} = 0$



Q5  $R_{xx}(\tau) = \frac{1}{T} \int_0^T x(t) x(t+\tau) dt$

$= \frac{1}{T} \left[ \int_0^\tau 0 * V dt + \int_\tau^T V^2 dt \right]$



$R_{xx}(\tau) = \frac{V^2}{T} (T - \tau) = V^2 \left( 1 - \frac{|\tau|}{T} \right)$

$-T \leq \tau \leq T$

Q6  $x(t) = V \sin(\omega t + \theta)$

$R_{xx}(\tau) = \frac{1}{T} \int_0^T (V \sin(\omega t + \theta)) (V \sin(\omega t + \omega \tau + \theta)) dt$

using  $\sin(x) \sin(y) = \frac{1}{2} (\cos(x-y) - \cos(x+y))$

$R_{xx}(\tau) = \frac{V^2}{2T} \int_0^T \cos(\omega \tau) - \cos(2\omega t + 2\theta + \omega \tau) dt$

$= \frac{V^2}{2T} \cos(\omega \tau) (T - 0) = \frac{V^2}{2} \cos(\omega \tau)$